# Blur Kernel Estimation using Deep Learning

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## Introduction Blur

- Blur is a distortion / degradation of images which results in unclear images that have lost features.
- 2. They can be classified into
  - a. Defocus (optical)
  - b. Motion



Motion Blur due to moving object

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Motion Blur due to camera jitter

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Defocus Blur due to incorrect focus in 3-D

## Introduction Uniform vs. Non-uniform Blur



Uniform

Non-uniform

## Introduction Uniform vs. Non-uniform Blur



Uniform (length = 10, angle = 45)



Non-uniform

## Introduction Image Deblurring

- 1. It is very challenging for a computer to do unsupervised Deblurring.
- 2. Blind Deconvolution techniques are severely under constrained as we need need estimate **h** and **F** given **G**.
- Blind Deconvolution works by first estimating the h also known as Point Spread function and then inverting using convolution or conjugate gradient methods.

$$\mathbf{G}(\mathbf{x},\mathbf{y}) = \mathbf{h}(\mathbf{x},\mathbf{y}) * \mathbf{F}(\mathbf{x},\mathbf{y}) + \mathbf{n}(\mathbf{x},\mathbf{y})$$

## Blur Kernel Estimation using Deep Learning



## Aim and Approach

#### AIM:

Estimating the non uniform blur kernel at each pixel using Convolutional Neural Networks (CNNs). Generating the sigma-map for a variantly blurred image.

#### **APPROACH:**

We train the CNNs to learn the sigma value of different gaussian blur kernels that model defocus blur. We start with training the CNN for 32x32 size patches and gradually reduce the patch size down to 1 pixel.

- 1. We used images from the Brodatz Textured Dataset
- 2. Each Image was blurred with a gaussian blur kernel with sigma from [0.3,0.6, ... ,3.0] taking any of the 10 discrete values.
- 32x32 size non-overlapping patches were sampled from these images to form the dataset.



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32x32 non overlapping patches taken from blurred images

## **Network Architecture**

th> model nn.Sequential { [input -> (1) -> (2) -> (3) -> (4) -> (5) -> (6) -> (7) -> (8) -> (9) -> (10) -> (11) -> (12) -> (13) -> (14) -> (15) -> (16) -> (17) -> (18)-> (19) -> (20) -> (21) -> (22) -> (23) -> (24) -> (25) -> (26) -> output] (1): cudnn.SpatialConvolution(1 -> 4, 3x3) (2): cudnn.ReLU (3): cudnn.SpatialConvolution(4 -> 8, 3x3) (4): cudnn.ReLU (5): cudnn.SpatialConvolution(8 -> 16, 3x3) (6): cudnn.ReLU (7): cudnn.SpatialConvolution(16 -> 32, 3x3) (8): cudnn.ReLU (9): cudnn.SpatialConvolution(32 -> 64, 3x3) (10): cudnn.ReLU (11): cudnn.SpatialConvolution(64 -> 64, 3x3) (12): cudnn.ReLU (13): cudnn.SpatialConvolution(64 -> 64, 5x5) (14): cudnn.ReLU (15): cudnn.SpatialMaxPooling(2x2, 2,2) (16): cudnn.SpatialConvolution(64 -> 64, 5x5) (17): cudnn.ReLU (18): nn.View(1024) (19): nn.Linear(1024 -> 1600) (20): nn.ReLU (21): nn.Linear(1600 -> 800) (22): nn.ReLU (23): nn.Linear(800 -> 100) (24): nn.ReLU (25): nn.Linear(100 -> 30) (26): nn.LogSoftMax

### Ramp Blur





#### Ramp Blur

#### RMSE: 0.2350







#### Ramp Blur

#### RMSE: 0.1645







### Ramp Blur RMSE: 0.000116



## Accuracy

Classes	Sigma Step Size	MSE	RMSE
10	0.3	0.0552	0.2350
30	0.1	0.0270	0.1645
		1.3506e-08	1.1621e-04



800



### Sin Blur RMSE: 0.1991







### Sin Blur RMSE: 0.1331







#### Difference



## Accuracy

Smoothing iterations	MSE	RMSE
0	0.0397	0.1991
1	0.0357	0.1891
12000	0.0177	0.1331

#### **Text Images**

### 1-D Sin Blur





Informally, the predicate word (p, q, m) in p has not sent agent q message m; intertion and p is in role r, containes (m, p, t)some containes attribute  $r_i$  and mindex that the message that attribute  $t_i$ from any  $t_1 \leq t_2$  index that attribute  $t_i$ from any  $t_2$ . We use standard the agent  $t_1 \leq t_2$  index that attribute  $t_i$ from any m usual in first order logic and Fwhere  $t_1$  and  $G_i = -p$  for "hence in teneral logic (e. 124). A formula

contains(m, p, l) | tagged(m, p $\varphi \land \varphi | \neg \varphi | \psi U \varphi | \varphi S \varphi | X \varphi$ 



#### **Text Images**

#### 2-D Sin Blur

al methods for precise and reproduc needed, as this factor is likely to eness (Kozel et al, 2000). In much of e of antidepressant effect, while of nt, has been below the threshold erman et al, 2000) and has not lived ed by encouraging results in anii the persistence of antidepressant effiek treatment period has rarely b lence suggests that the beneficial effitaking the development of maintena f rTMS is to become clinically applica er nonconvulsive rTMS has antidep lence from its clinical unafulness in







## Natural images with defocused background



## Natural images with defocused background



## Natural images with defocused background



## Natural images with defocused foreground



## Natural images with defocused foreground



## Conclusion

- 1. We see that the model is able to learn 30 classes and gives a coarse prediction of the sigma map.
- 2. We can getter better results if we reduce the quantization level to 60 classes.
- 3. Ideally, Blur Kernel Estimation is a regression problem. In the future we hope to use Fully Convolutional Networks.

